

MULTI-ROTOR CONTROLLER SYSTEM

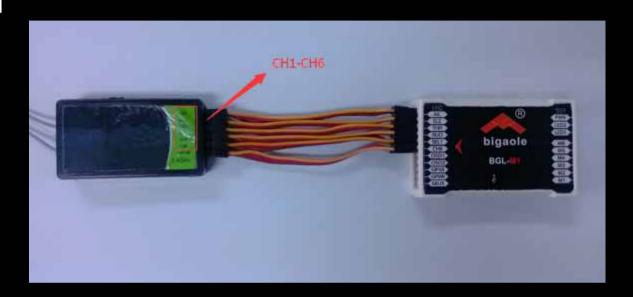
BGL-M1

Packing list

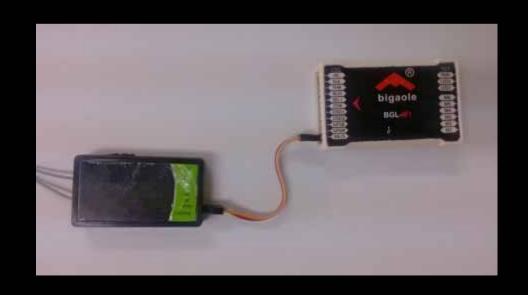
- A. Main control x1
- B. GPS compass module x1
- C. Multifunctional power module x1
- D. Wire 1 x6 (connect receiver)
- E. GPS bracket x1
- F. Double side sticky pads x4



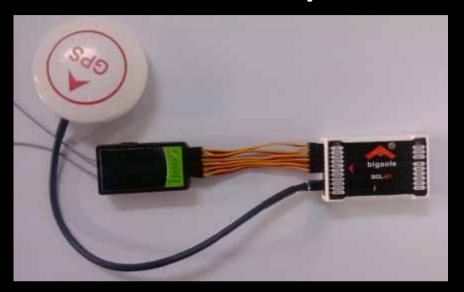
- Connect Main control with receiver
- The picture is Futaba receiver connection.



Support S-bus connection. (if you use S-bus connection, remember to select the receiver type on assistant software later.)



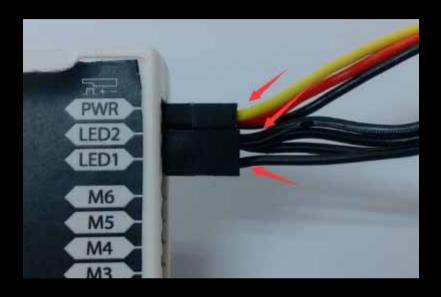
Connect GPS compass module



• The white line and blue line side is on top as picture.



- Connect multifunctional power module
- Yellow line side on top connect PWR.
- Three signal line side connect LED2
- One signal line side connect LED1



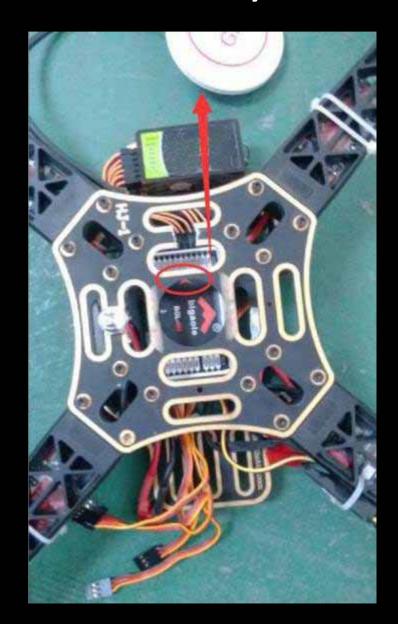


Mount main control
 on your aircraft with
 double side sticky pads

Remarks:

a. Try to keep the main control at your aircraft's center of gravity and parallel to the aircraft body.

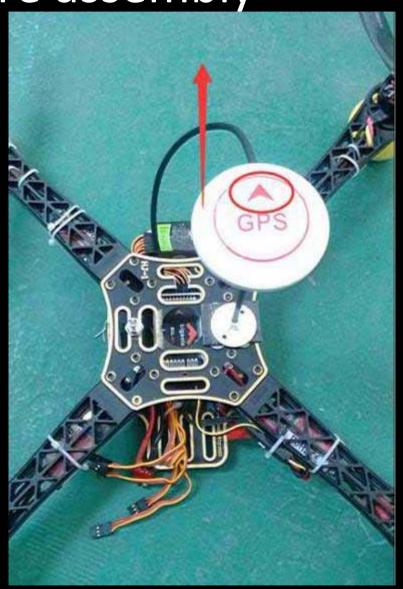
b. Arrow direction on main control is consistent with the multi rotor's front side.



 Mount GPS compass module on your aircraft with GPS bracket and double side sticky pads

Remarks:

a. Arrow direction on GPS module is consistent with the multi rotor's front side.b. Keep GPS module as far as possible from the high current and strong magnetic field environment, which produced by ESC when it working



 Fix your receiver on your aircraft with double side sticky pads or some other material.

• Fix Multifunctional power module on your aircraft.

Hardware assembly is finished now!



- Close all mix-function
- Select a 3 position switch as CH5
- Select a 2 position switch as CH6

 Check channel if is reversed (AILE, ELEV, RUDD, CH5, CH6)

 The picture is Futaba transmitter for your reference. • AILE value left to Right, 900US to 2100US



• ELEV value top to down, 900US to 2100US



 Check channel if is reversed (AILE, ELEV, RUDD, CH5, CH6) RUDD value left to Right, 900US to 2100US



• The picture is Futaba transmitter for your reference.

CH5, UP position, 900US< CH5 <1200US:
 Manual mode



 Check channel if is reversed (AILE, ELEV, RUDD, CH5, CH6) CH5, Medium position, 1200US < CH5
 <1800US: GPS hovering mode

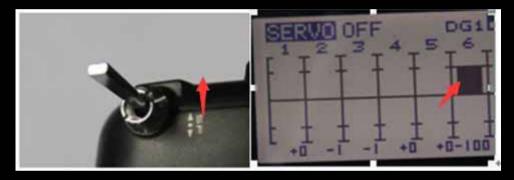


• The picture is Futaba transmitter for your reference.

CH5, Down position, 1800US<CH5 <2100:
 Return home mode

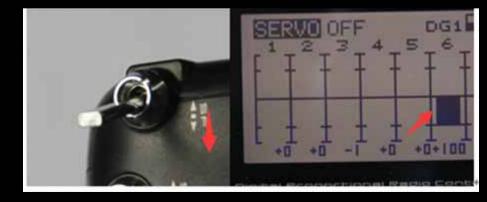


 Check channel if is reversed (AILE, ELEV, RUDD, CH5, CH6) CH6, Up position, 900US< CH6 < 1520US
 Head mode



 The picture is Futaba transmitter for your reference.

CH6, Down position, 1520US< CH6< 2100:
 Headless mode

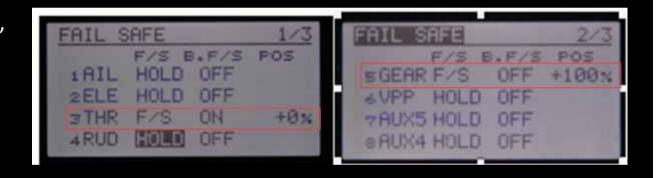


Fail safe setting

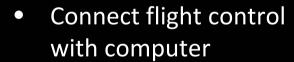
Find Fail Safe menu

Setting AIL, ELE, THRO, RUDD, GEAR value

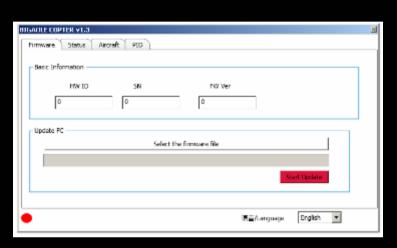
Here is an example of FUTABA T8FG



Open COPTER V1.3 on your computer



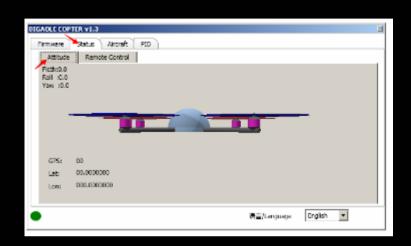
• PS. The interface of flight control (Micro USB) support most of mobile phone's charging cable.



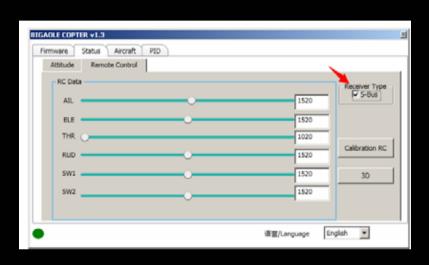


- Menu-→State
 - -→Attitude

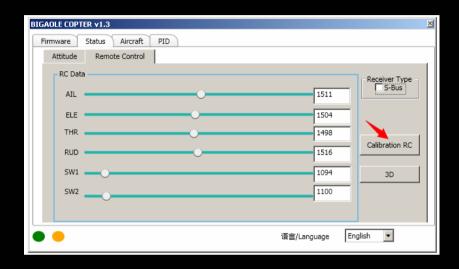
Rotate your aircraft to three direction according to Aileron(ROLL), Elevator(PITCH), and Rudder(RAW), check multi-rotor gyroscope's three axis' adjustment.



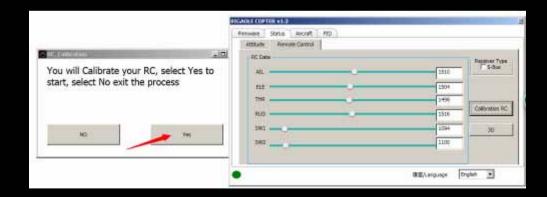
 If you connect main control with receiver by S-bus, please remember to select the receiver work method with S-bus type.



 Transmitter calibration press the calibration button



Press the yes button



• Transmitter calibration

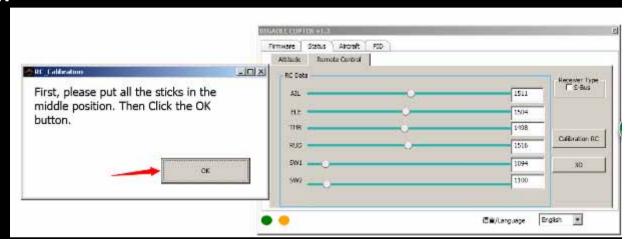
Put all the sticks in the middle position.

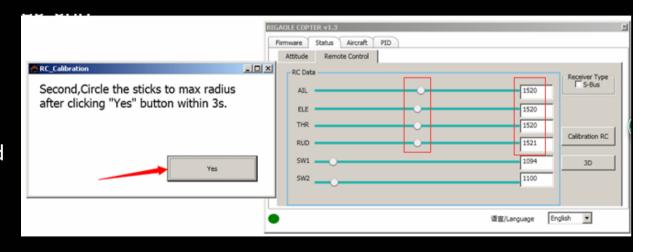
Press the ok button

After AIL, ELE, THR, RUD value number adjust to around 1520 automatically.

Press the yes button and circle the sticks to max

radius sticks within 3s.



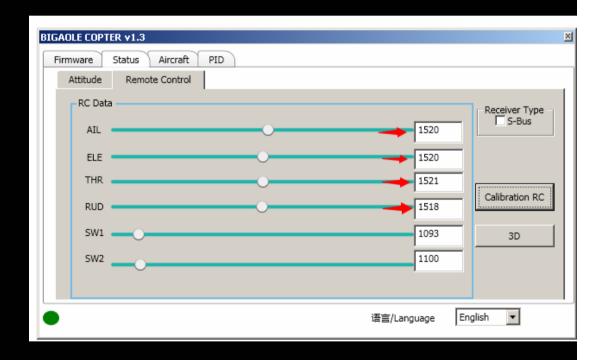


• Transmitter calibration

Calibration finished, and you will find the data on picture.

AIL, ELE, THRO, and RUD values are in the range of about 1520, up and down a few errors.

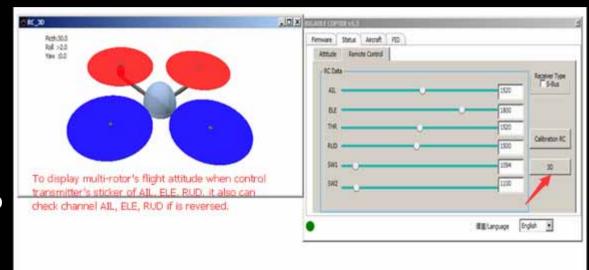
If not, please recalibrate.



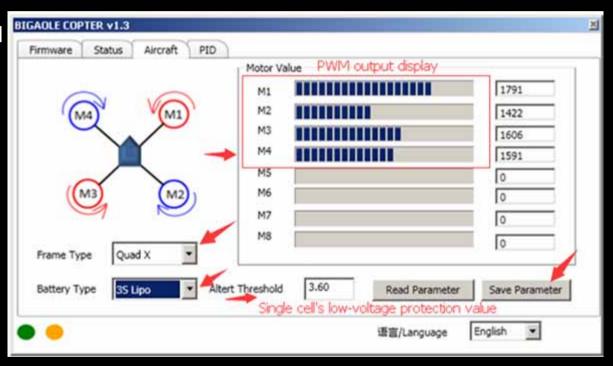
 Check transmitter channel if is reversed.

Press 3D button.

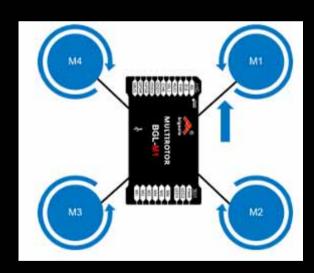
Control transmitter's sticker of AIL, ELE, RUD, to see if the channel is reversed.

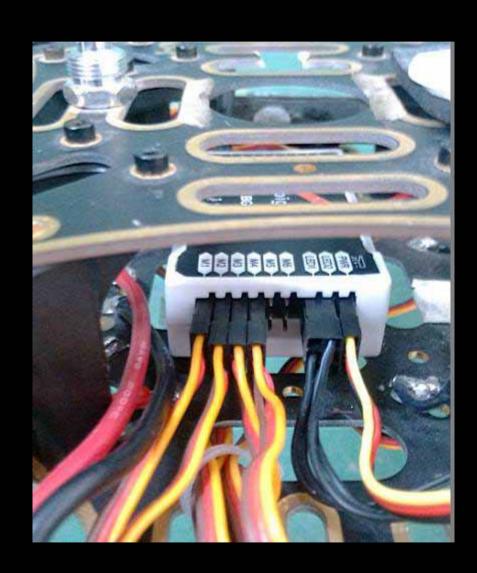


- Menu-→Aircraft
- Select aircraft type, battery cell number, and single cell's low-voltage protection value.
- Check M1-M4 PWM output
- Save Parameter



 Connect M1-M4 with flight control.





Check M1-M4
 propeller's installation

 if is correct.



 Connect battery, and multifunctional power module

Always remember that power your transmitter on first, off last!



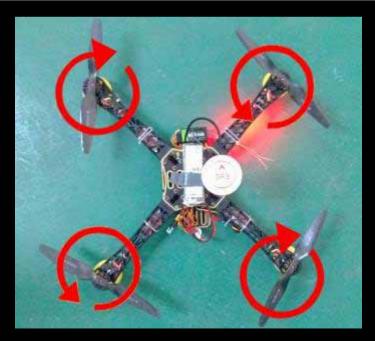
Unlock aircraft

Pull the throttle stick to the lowest

Operate AIL, ELE, RUDD channel stick can unlock the aircraft like picture.

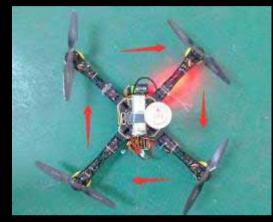
3
4+1

Check M1-M4 rotating direction if is correct.



• Compass Calibration

Place the aircraft on level ground
Clockwise / unclockwise rotation paralleling to the horizontal ground for 3 or 4 loops





Can also calibration compass in the Air, the method please check our manual.

• Gyro Calibration

- a. Keep the aircraft on level ground and remain stationary.
- b. Switch the 3 position switch(CH5) between manual flight mode and hovering mode for four times, the LED becomes solid white.
- c. Wait for white LED disappear.

Gyro Calibration is completed.

(Calibration of magnetic field and gyro are saved at the same time.)





• Check GPS satellite status.

red led double flash or triple flash, means GPS signal is good.

You can try to fly now!



Test-fly

• Aircraft test-fly based on flight control's default parameter when it come out of factory.

• If you do not satisfied with the aircraft performance, please make Parameter adjustment by assistant software, more details please check part 6 of in our manual.

Above installation steps is for your reference, if you have any problem during your installation, please kindly contact us by service@bglmodel.com.

Thank you!